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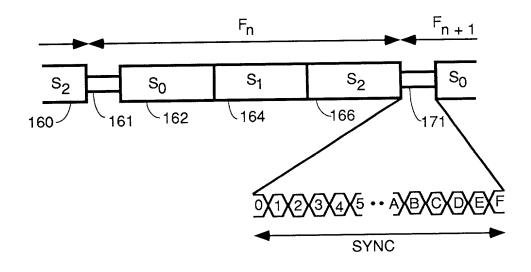


FIG. 2A

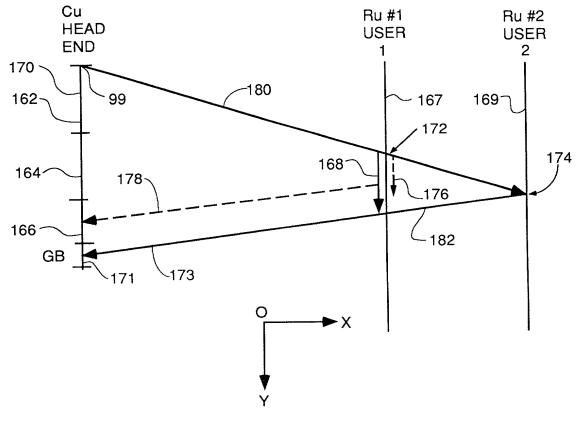
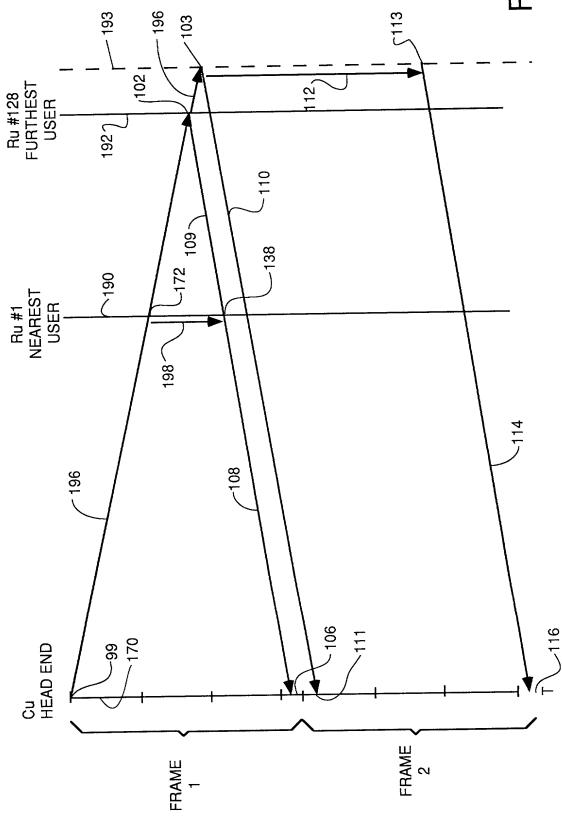


FIG. 2B

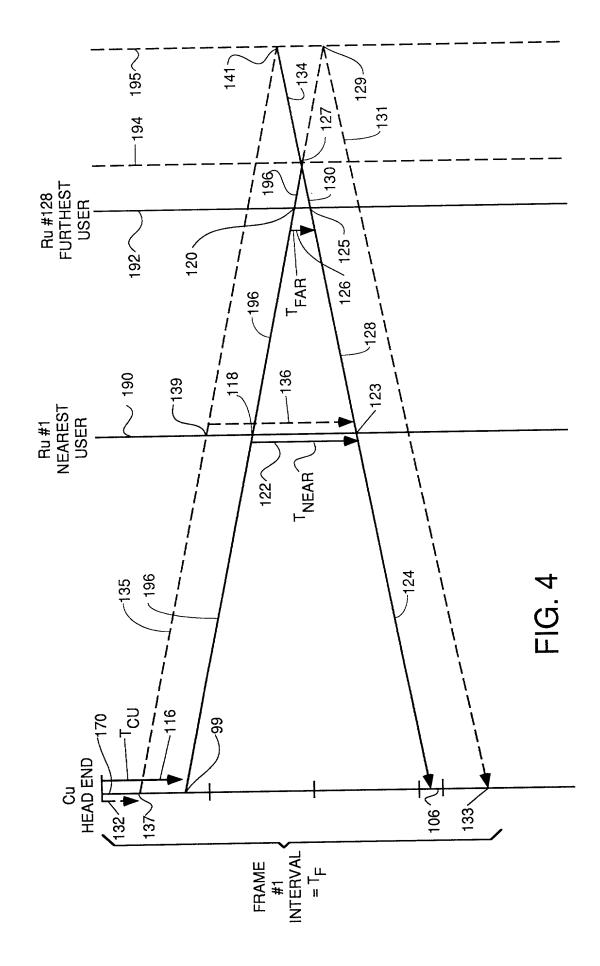
7

* i

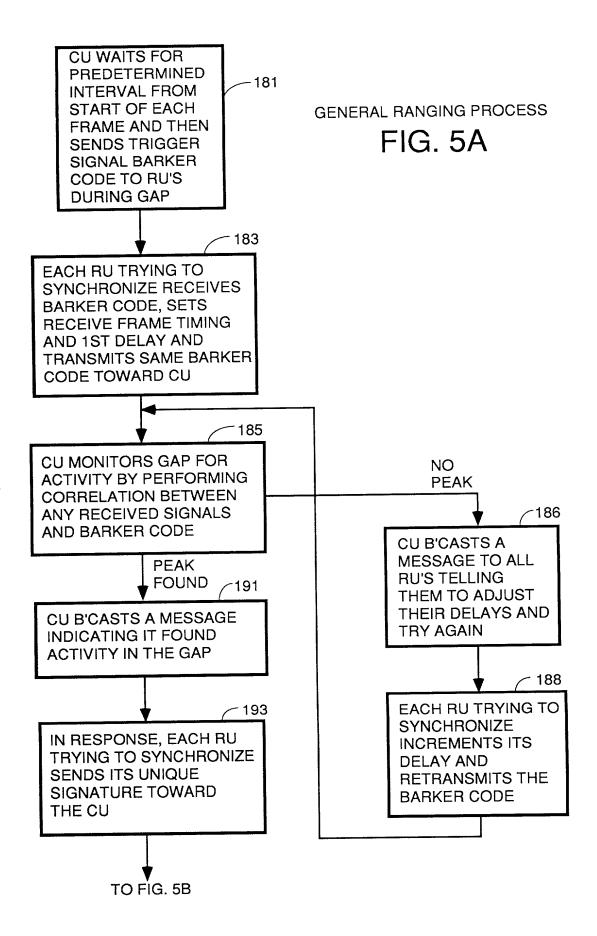


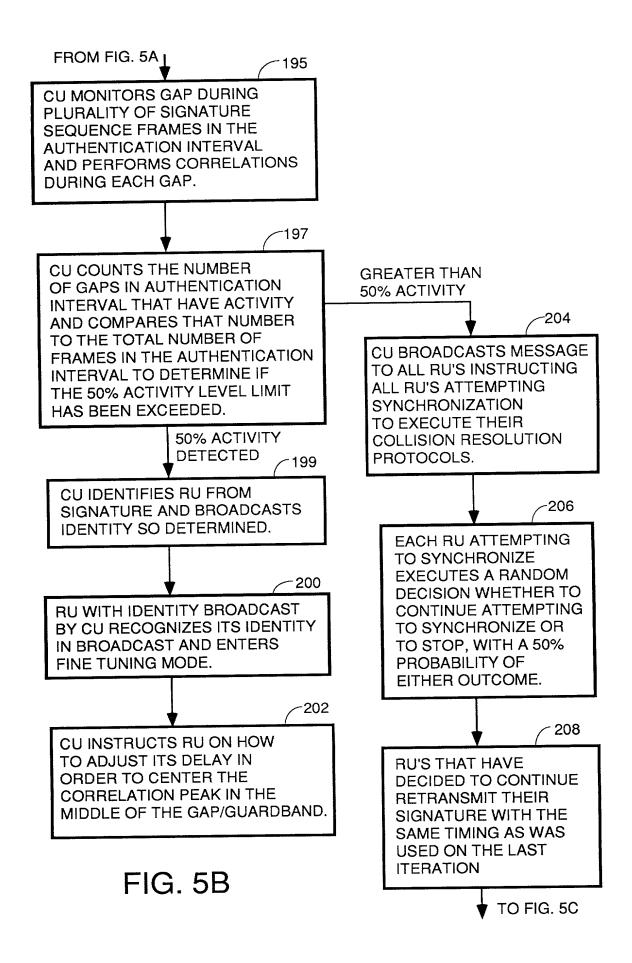
¥ •

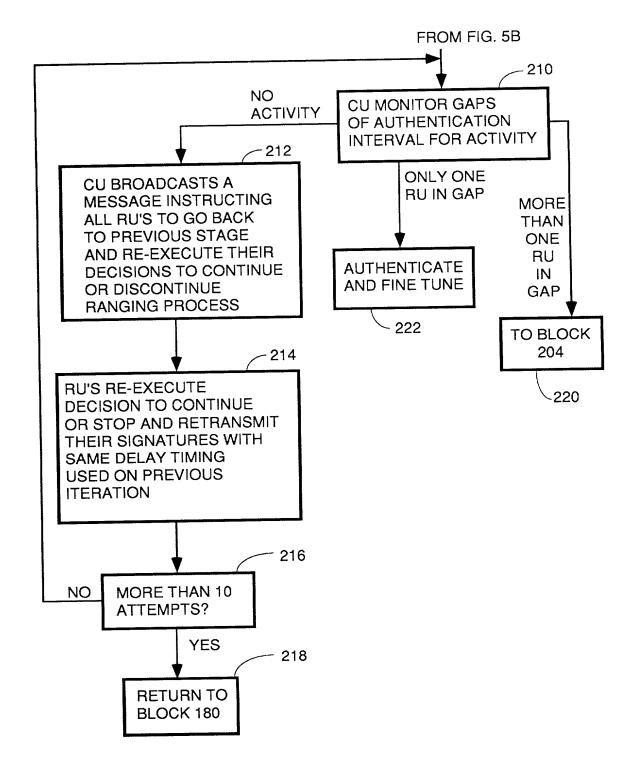
*



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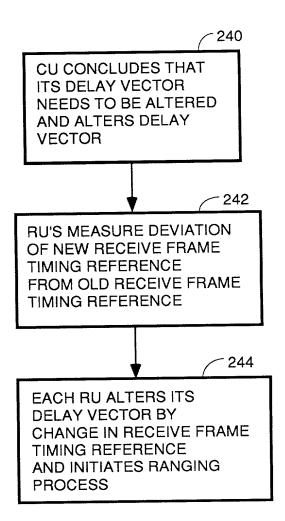


FIG. 6 DEAD RECKONING RE-SYNC

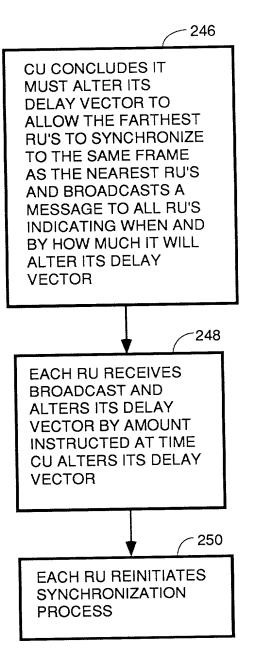
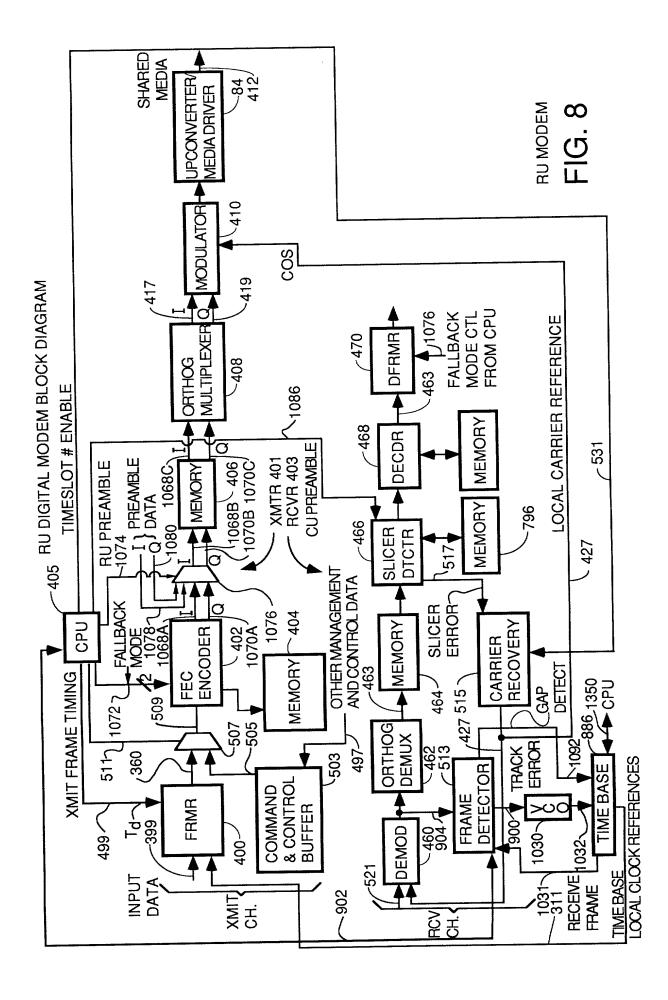
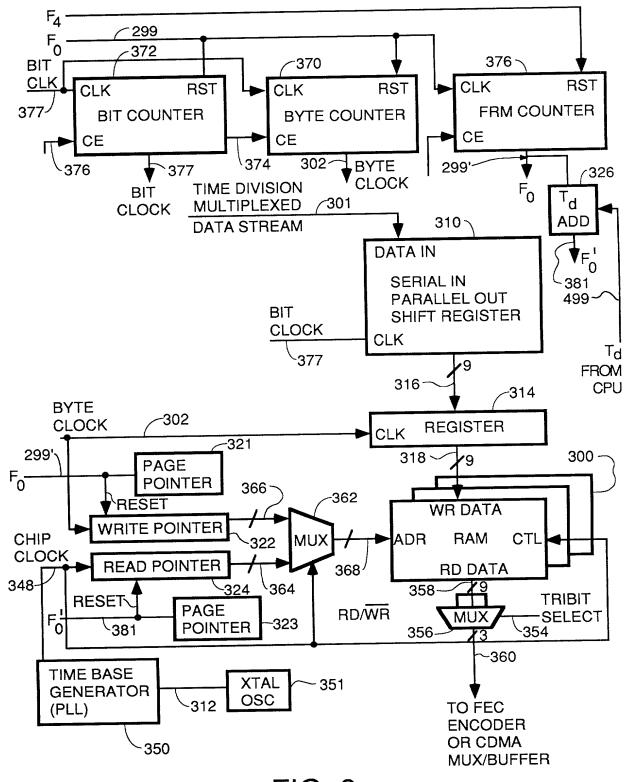


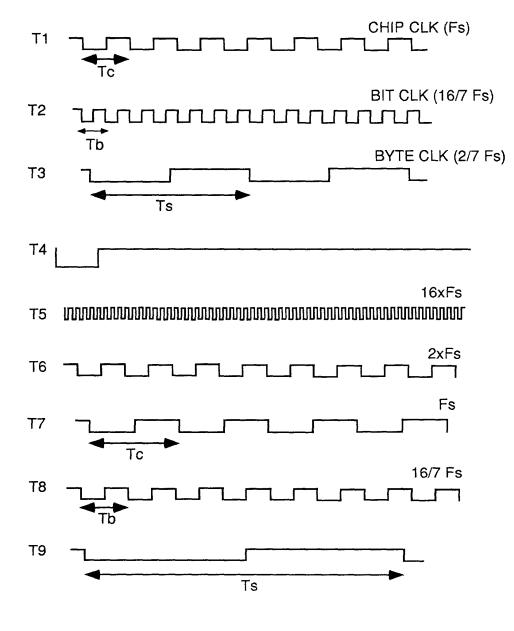
FIG. 7 PRECURSOR EMBODIMENT

The line from the start of the

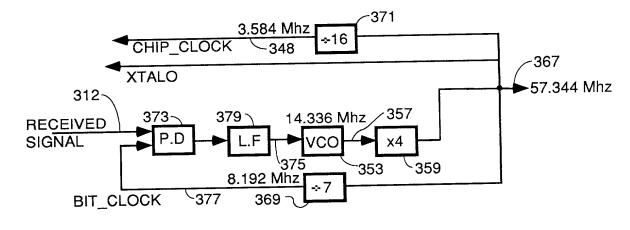




THE OKENIC



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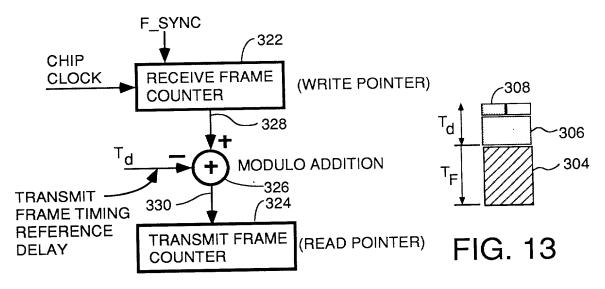
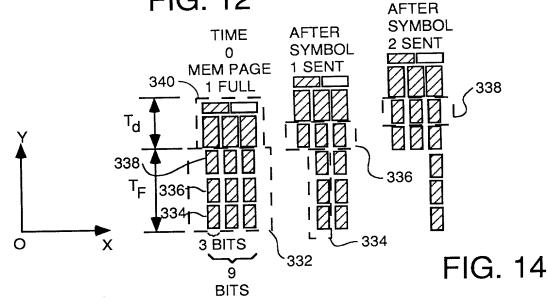
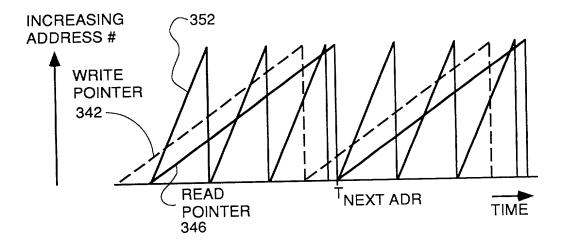


FIG. 12





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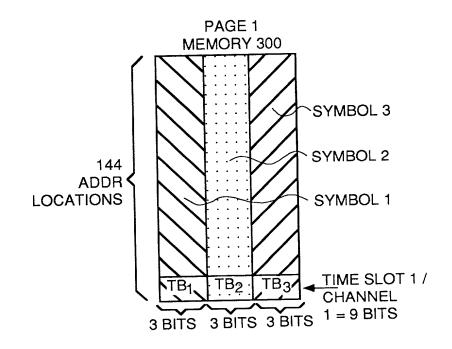
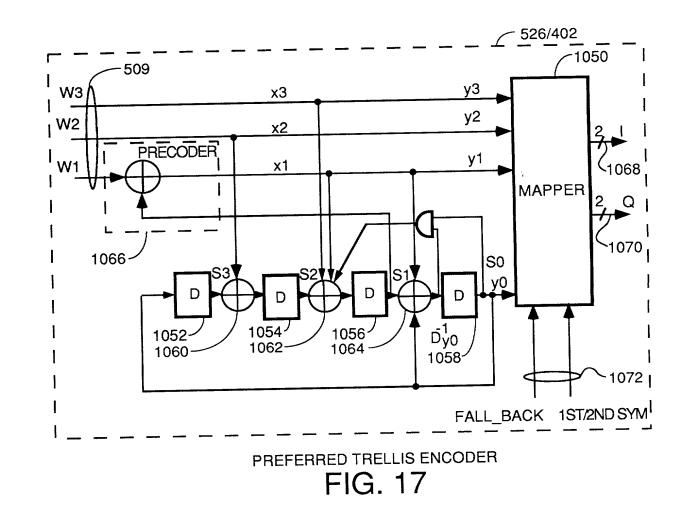
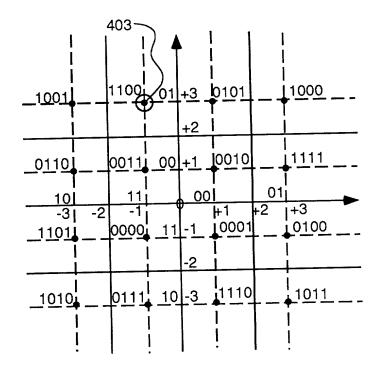


FIG. 16

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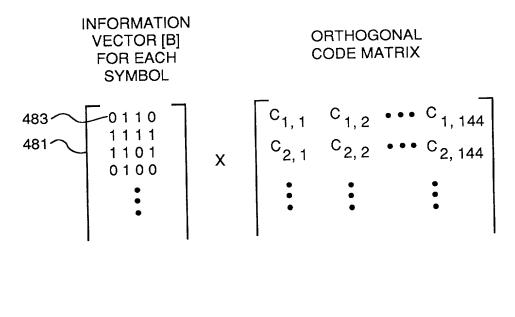
•

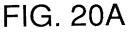




| 0000 | 111 | 111 | · · · · · · · · · · · · · · · · · · · |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------|
| | | 111 | = 1 - j |
| | | 001 | <u>= 1+j</u> |
| | 111 | 001 | <u> </u> |
| the second s | 011 | 111 | <u>= 3-j</u> |
| | 001 | 011 | <u>= 1+3*j</u> |
| the second s | 101 | 001 | = -3 + j |
| | | 101 | <u>= -1 - 3* j</u> |
| the second s | | 011 | <u>=+3 + 3*j</u> |
| | | 011 | <u>= -3 + 3*j</u> |
| | | 101 | = -3 - 3* j |
| - Contraction of the local division of the l | | 101 | = 3 - 3* j |
| | | 011) | = -1+ 3* j |
| | | 111 | = -3 - j |
| and the second division of the second divisio | | 101 | = 1-3*j |
| | | 001 | = 3 + j |
| | 0000 0001 0010 0011 0100 0101 0110 0111 1000 1001 1010 1011 1100 1111 1110 | $\begin{array}{c cccc} 0001 & 001 \\ \hline 0010 & 001 \\ \hline 0011 & 111 \\ \hline 0100 & 011 \\ \hline 0101 & 001 \\ \hline 0101 & 001 \\ \hline 0110 & 101 \\ \hline 0111 & 111 \\ \hline 1000 & 011 \\ \hline 1001 & 101 \\ \hline 1010 & 101 \\ \hline 1011 & 011 \\ \hline 1100 & 111 \\ \hline 1101 & 101 \\ \hline 1110 & 001 \\ \hline \end{array}$ | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ |

`.





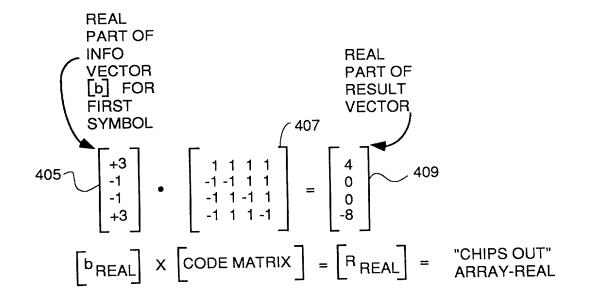
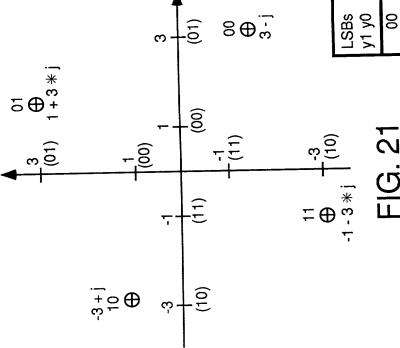


FIG. 20B

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MAPPING FOR FALL-BACK MODE - LSB'S



-<u>1-</u>]3

F

1+j3 -3+j

6 0

180 6-

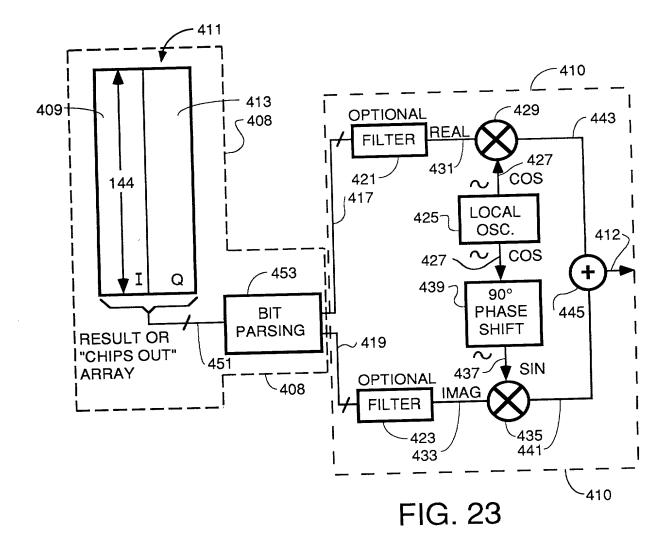
9 5

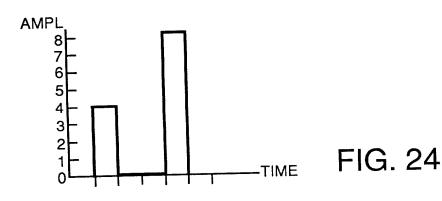
.-ا

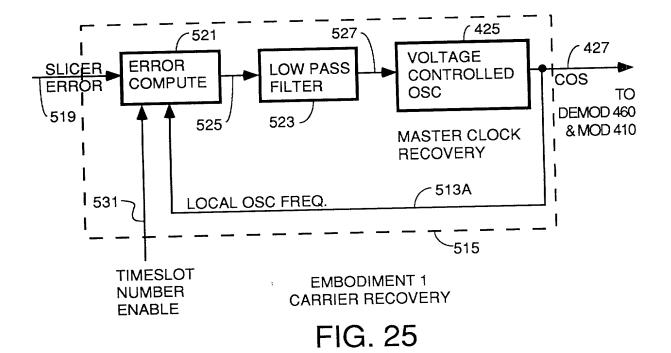
| _ | | | | _ | | |
|---|--------------|---------------------|-------|-------|-------|-------|
| (| 1+JC WHEN | LSB=11 | -1-j3 | 3-j | 1+j3 | -3+j |
| | 1+jQ WHEN | LSB=10 | -3+j | -1-j3 | 3-j | 1+j3 |
| | 1+jQ WHEN | | 1+j3 | -3+j | -1-j3 | 3-j |
| | 1+jQ WHEN | LSB=00 | 3-i | 1+j3 | -3+j | -1-j3 |
| | difference | (2nd-1st symbol) | 0 | 06 | 180 | 06- |
| | MSBs | y3 y2 | 8 | 01 | 10 | 11 |

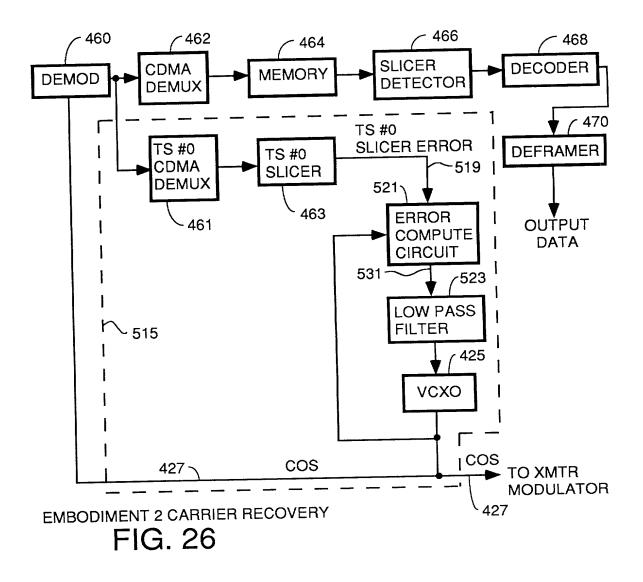
1+jQ

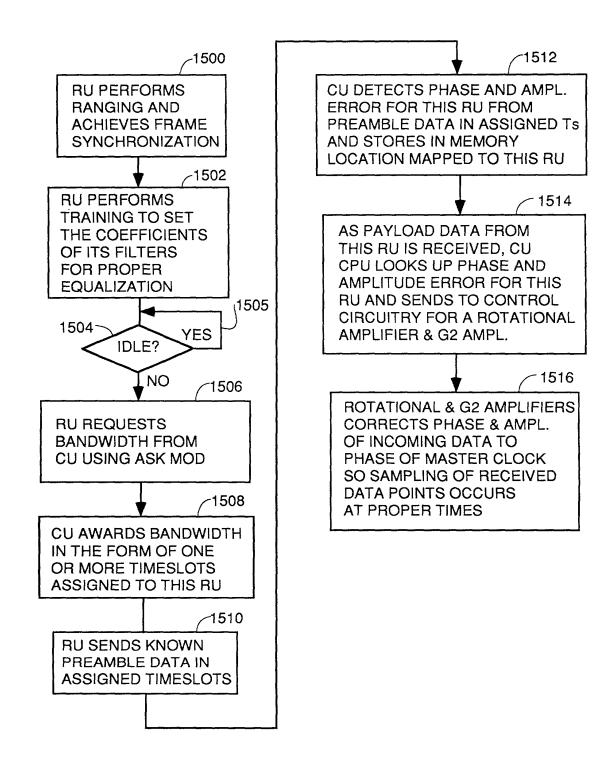
PHASE

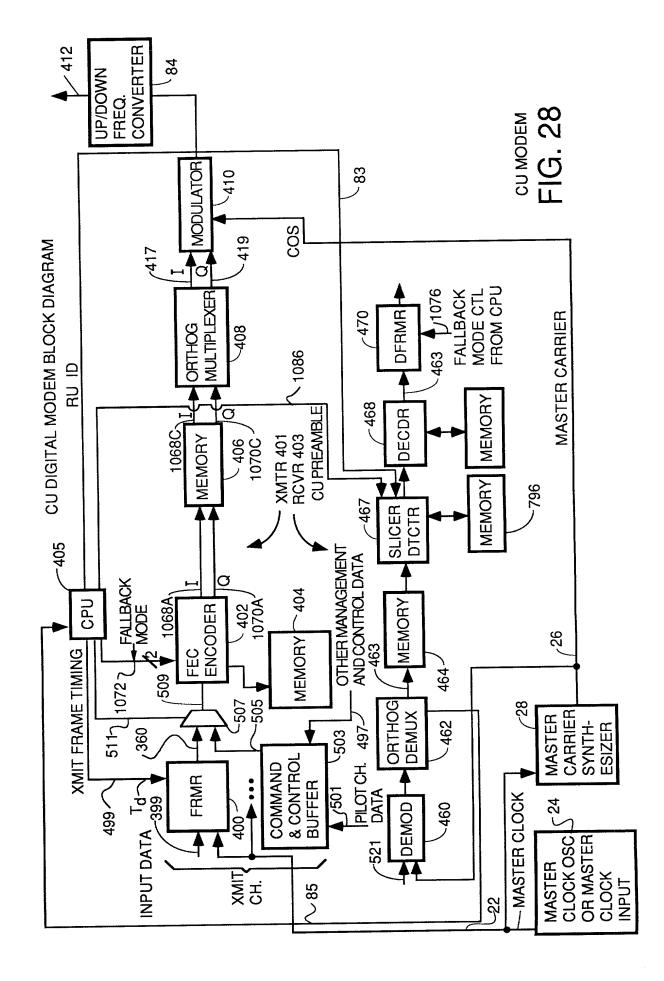




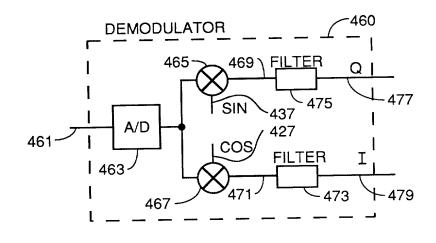






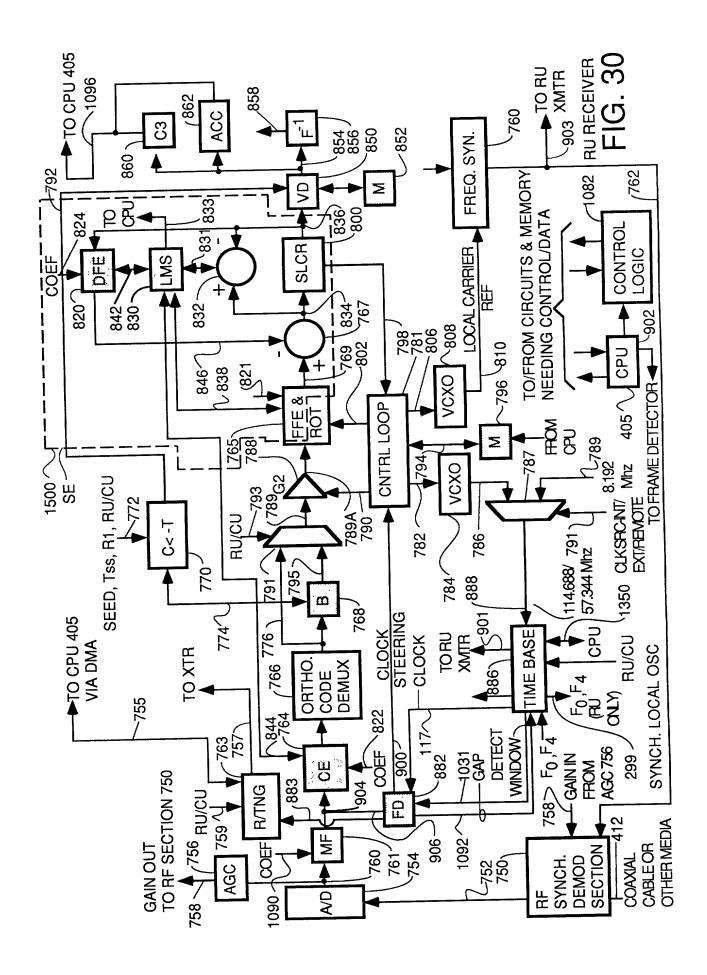


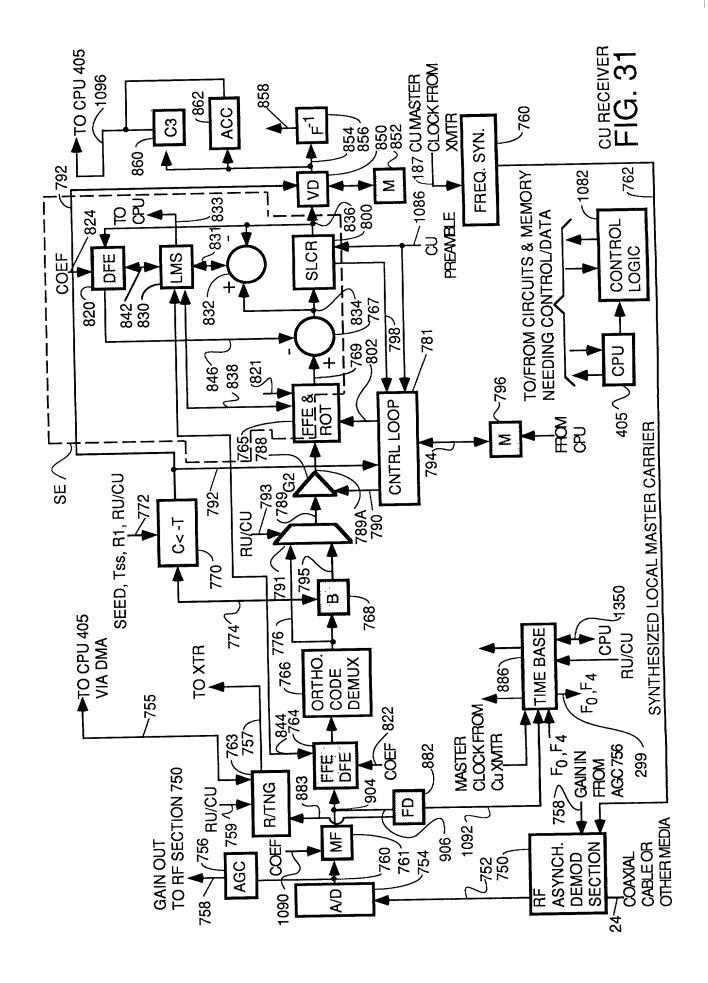
the first first

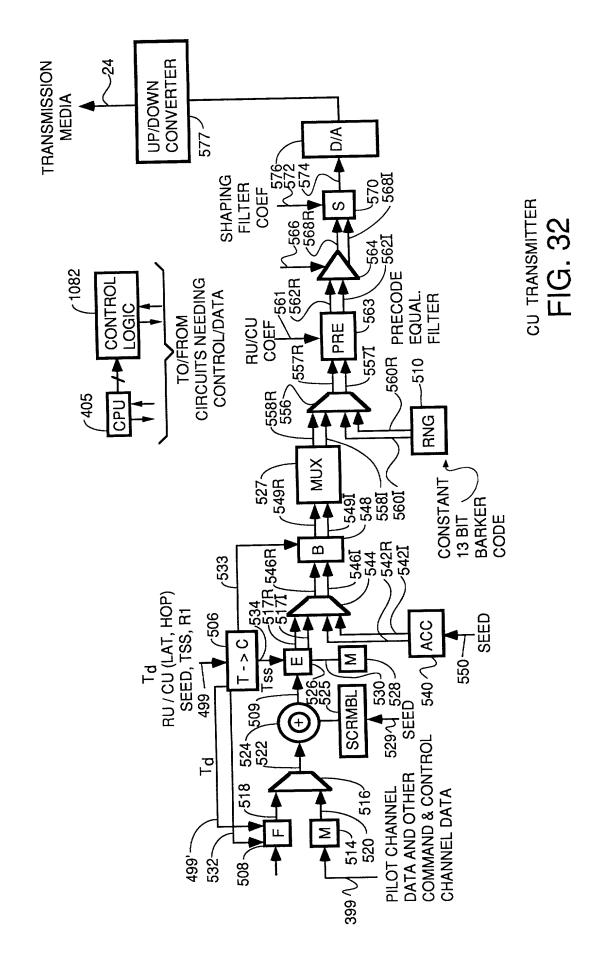


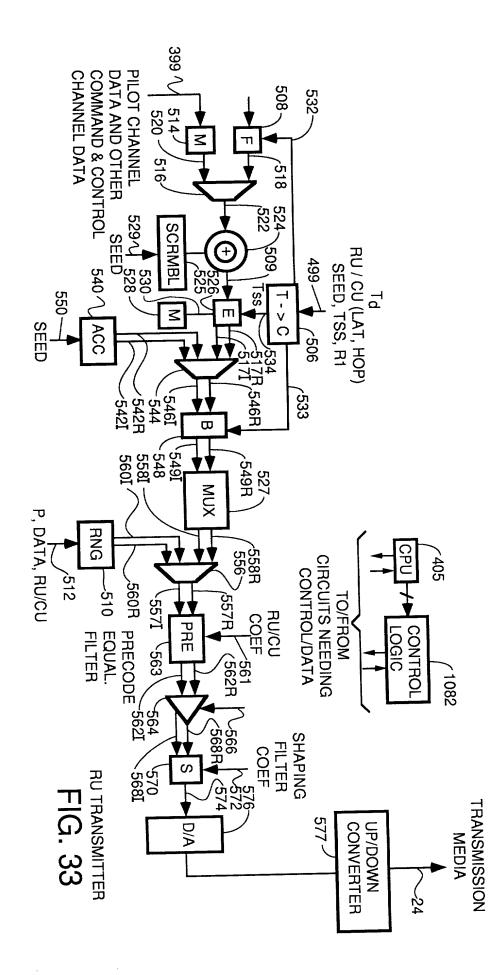


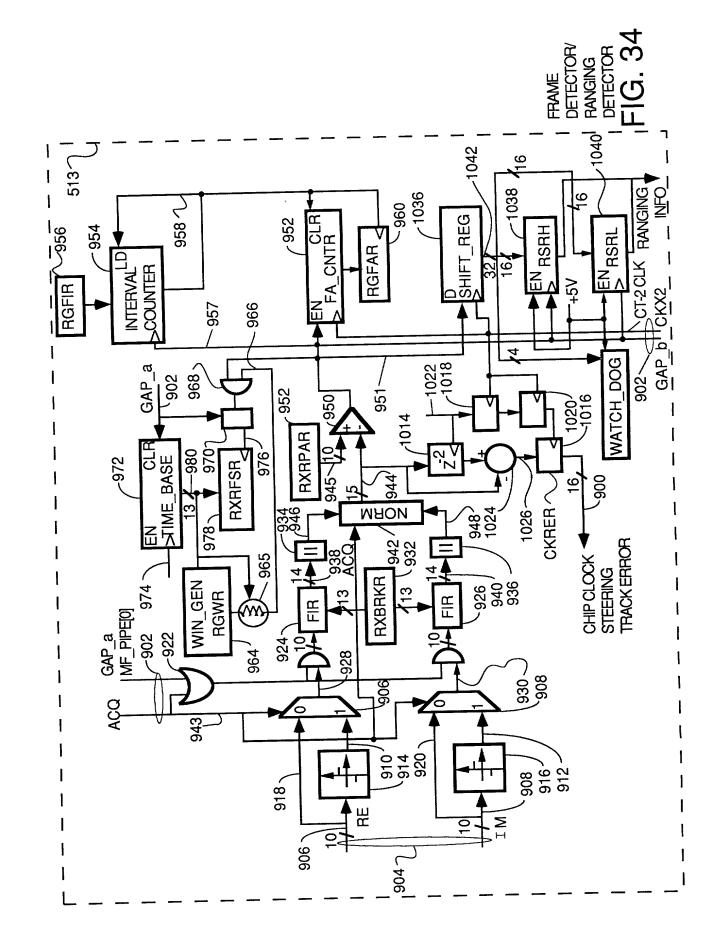
•

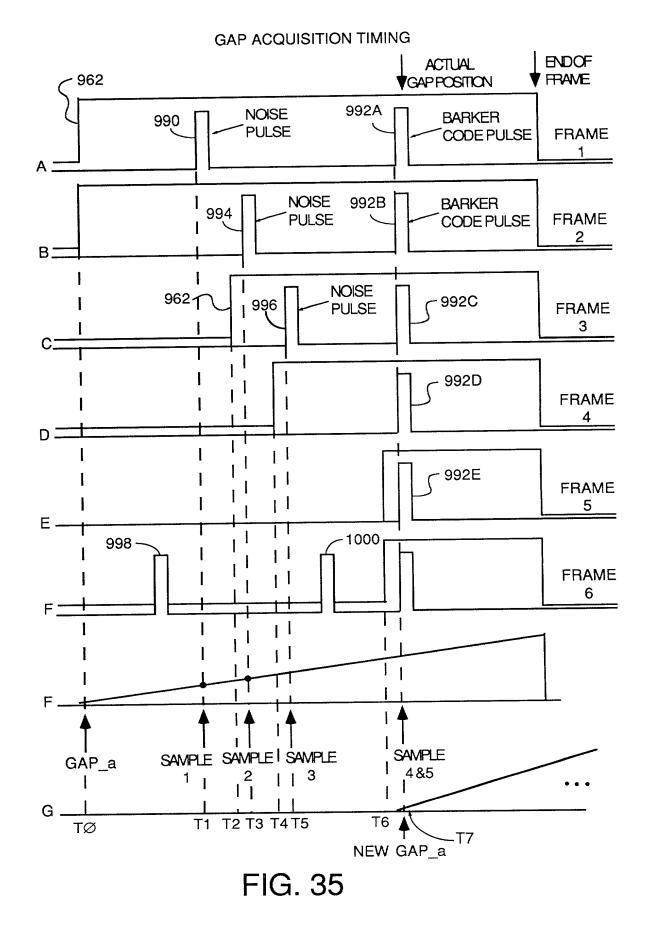












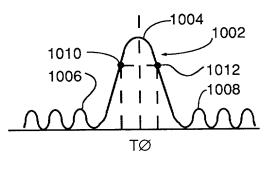


FIG. 36

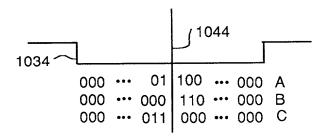
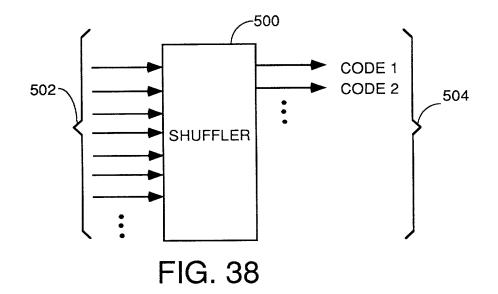
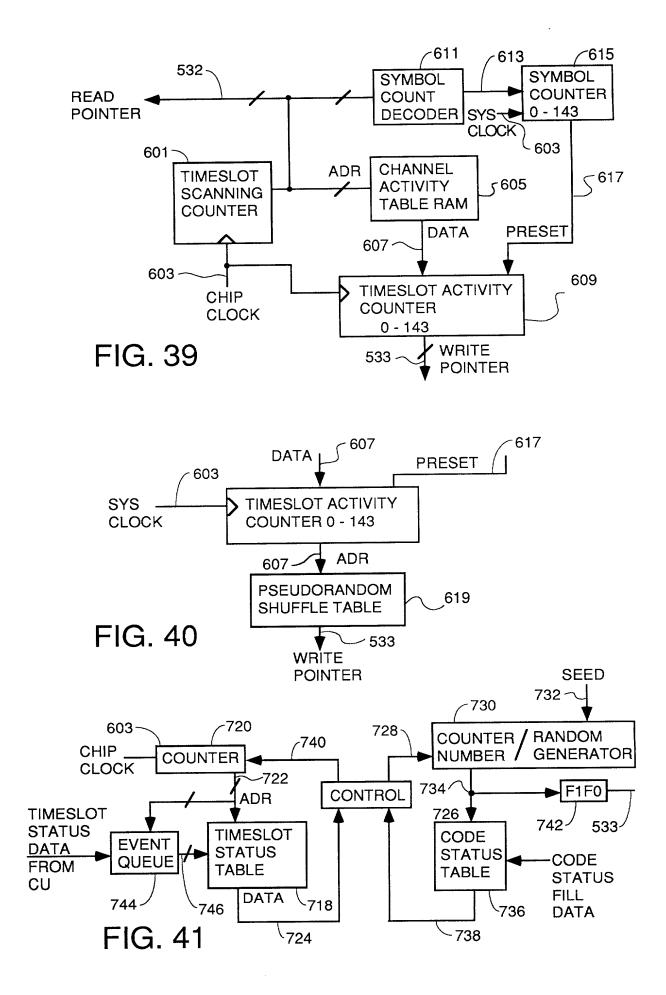
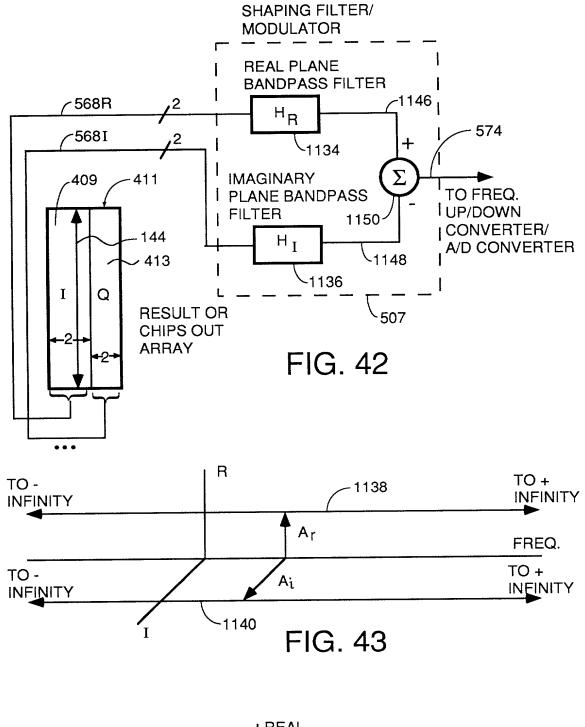
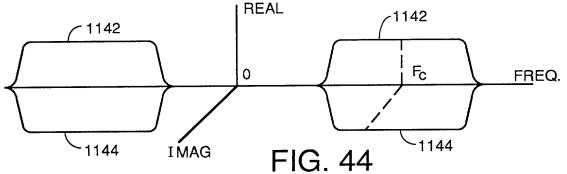


FIG. 37 FINE TUNING TO CENTER BARKER CODE

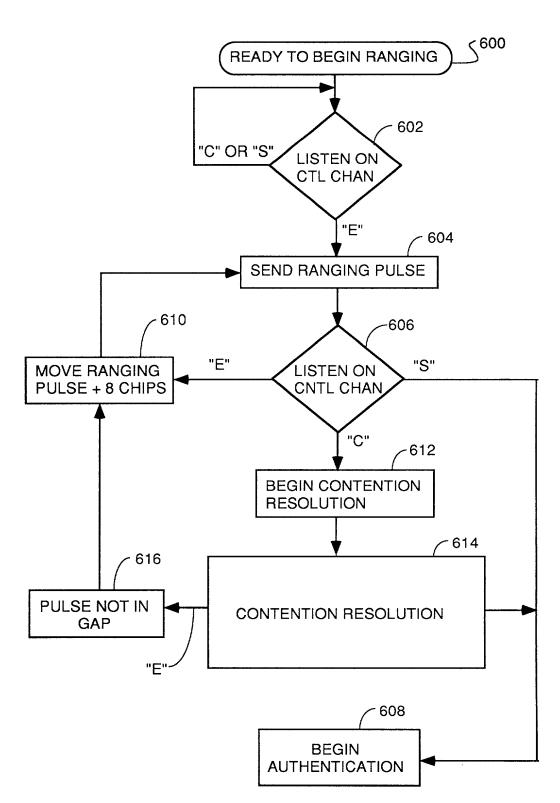




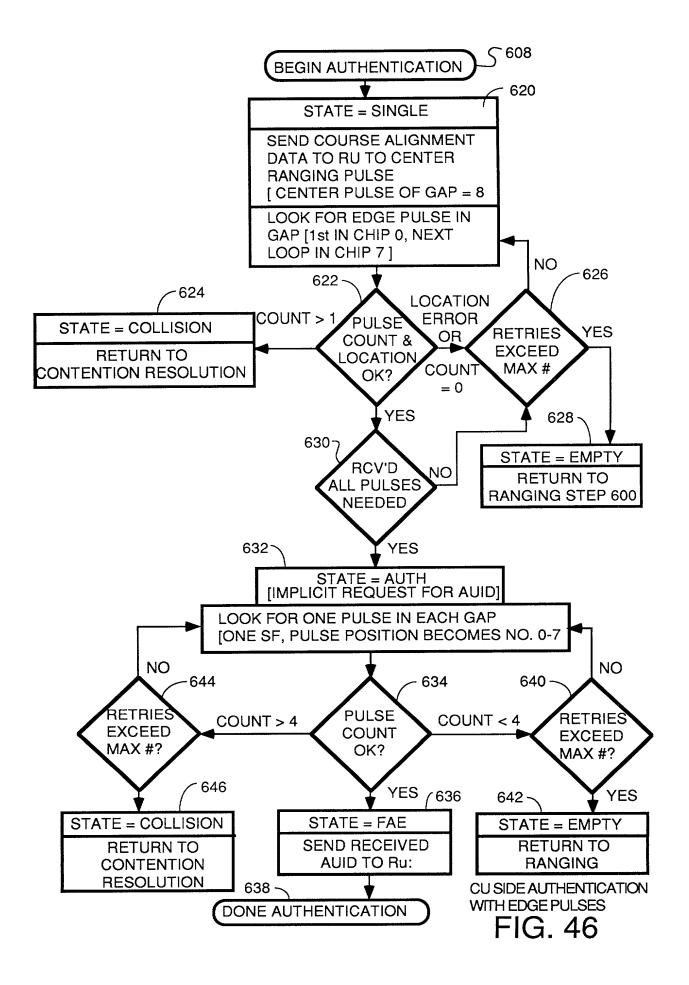


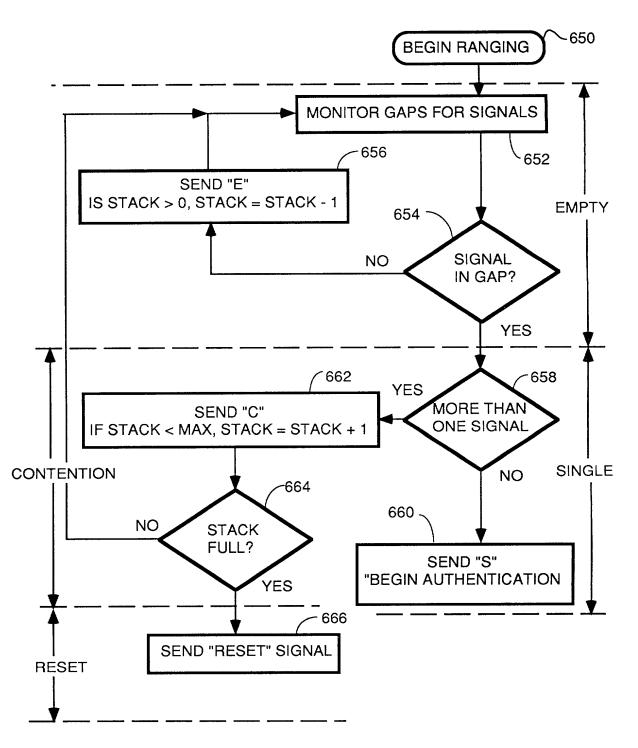


•



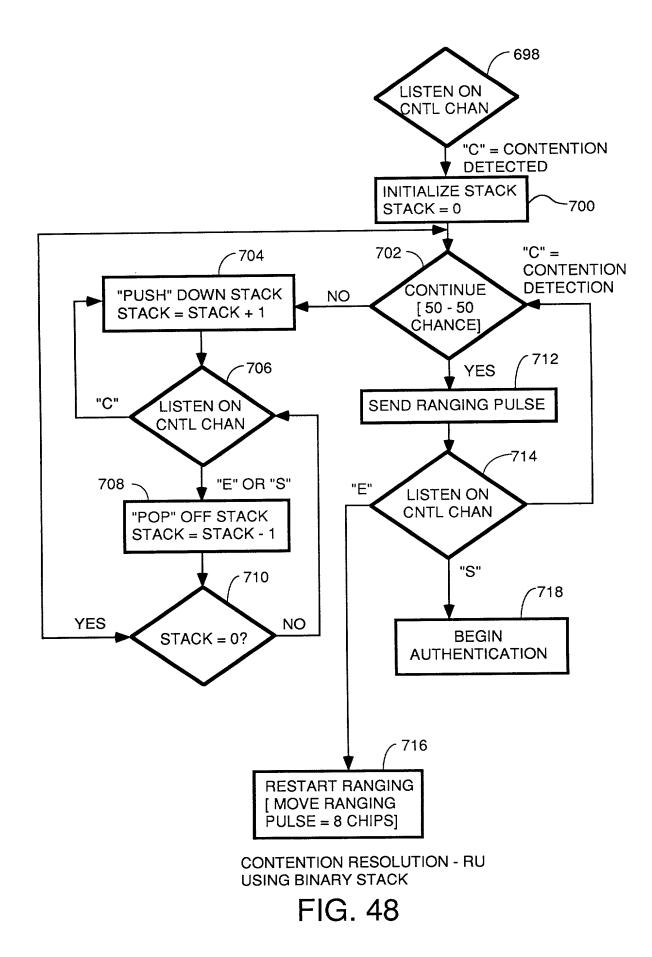
ru ranging FIG. 45

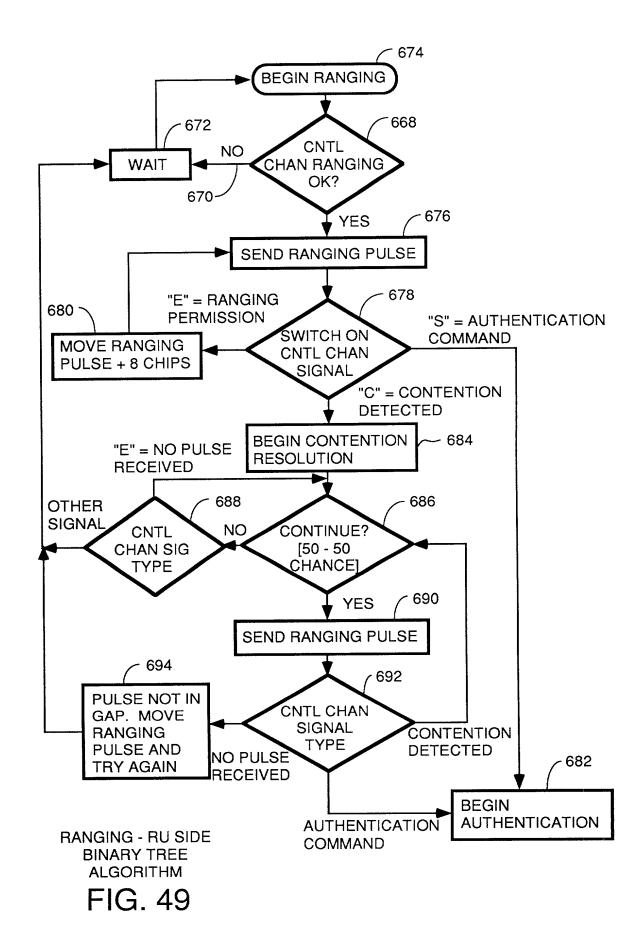


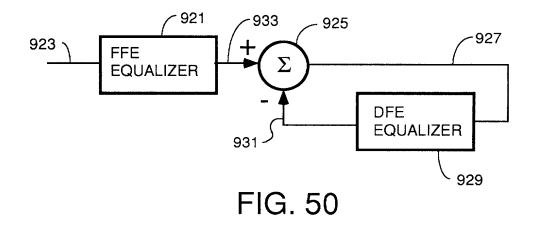


CU RANGING AND CONTENTION RESOLUTION

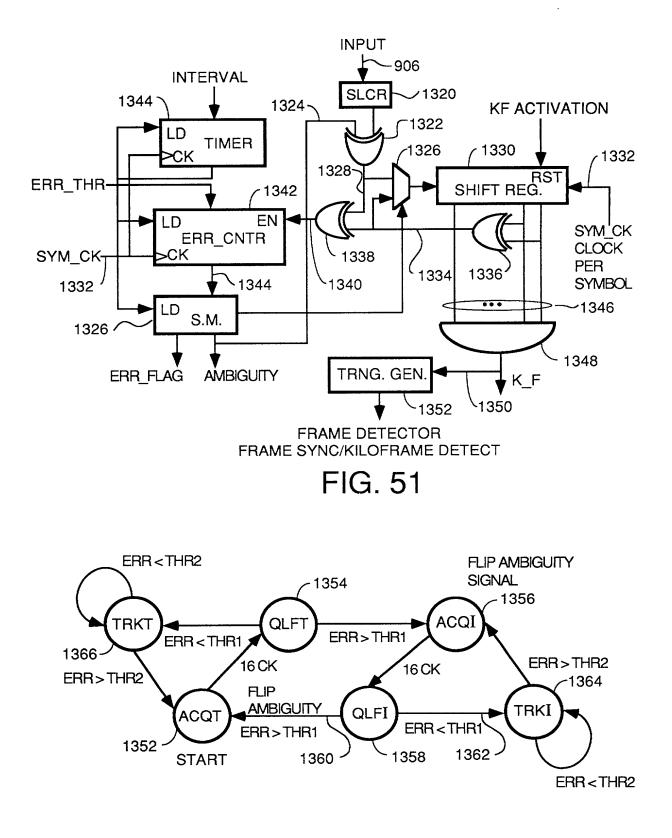
FIG. 47



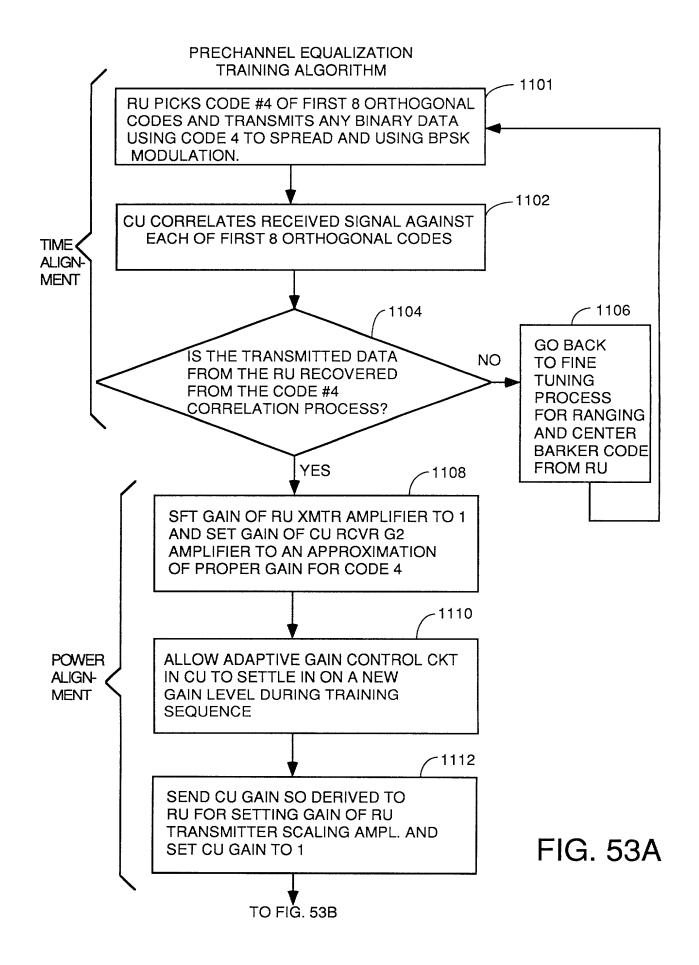


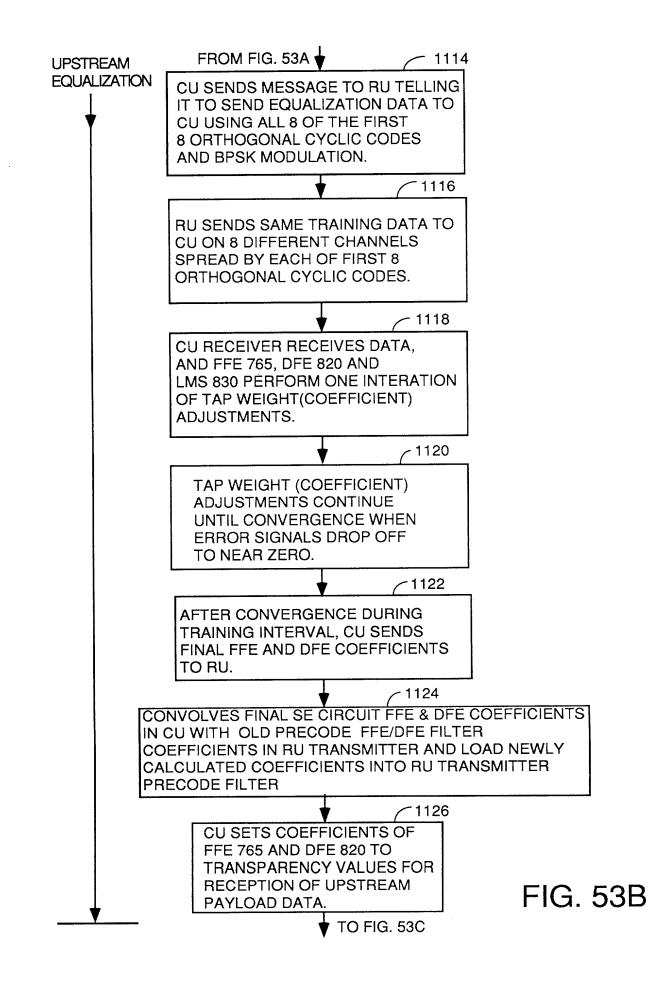


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STATE MACHINE FIG. 52





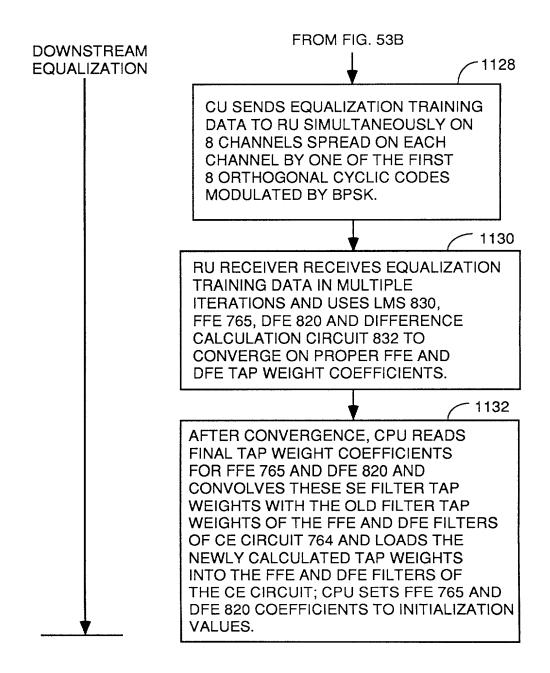


FIG. 53C

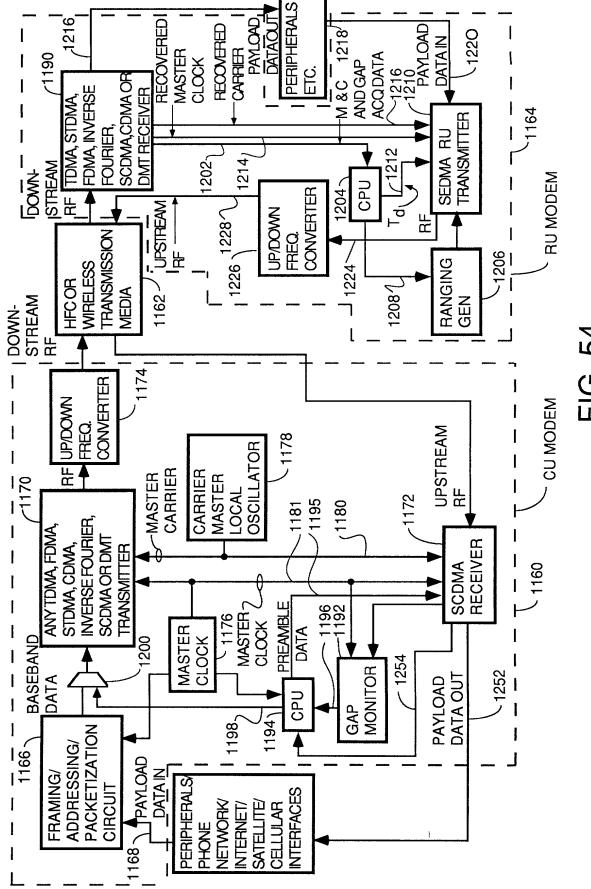
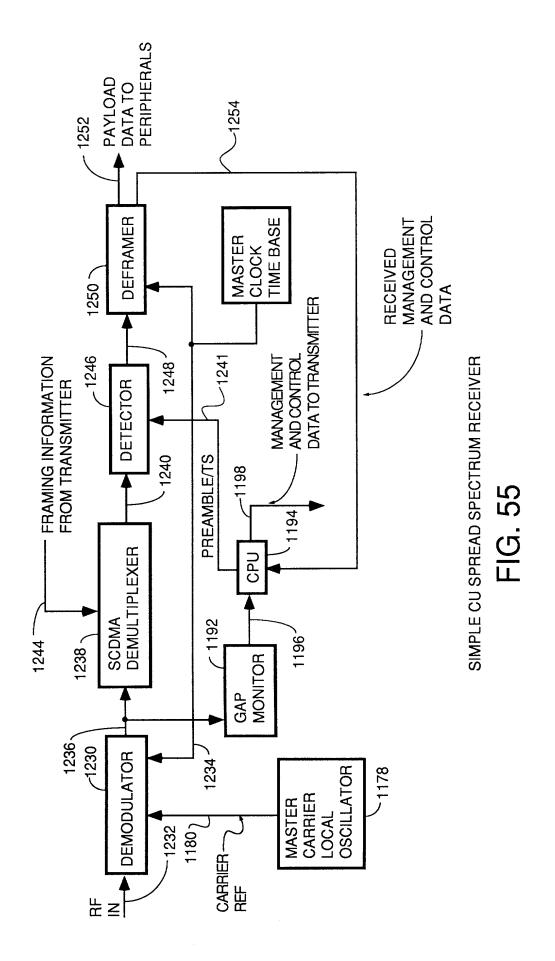


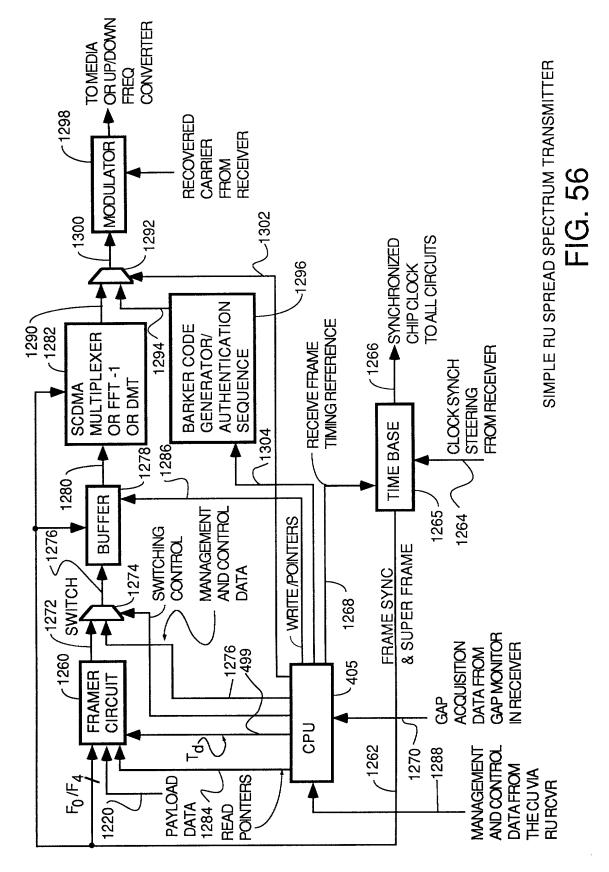
FIG. 54



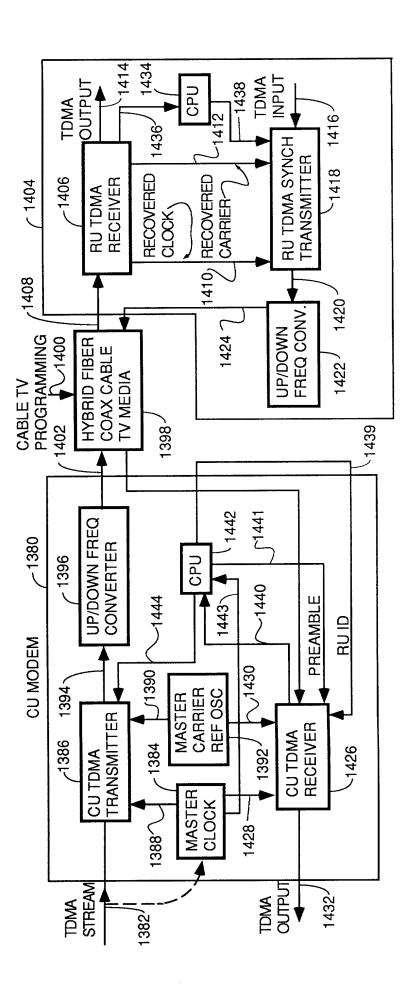


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SYNCHRONOUS TDMA SYSTEM FIG. 57

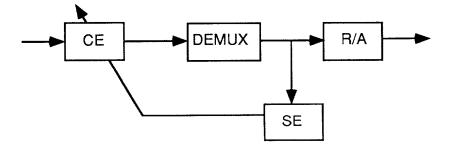


| OFFSET | 1B . | ASIC | 2A ASIC | | | |
|---------|--------|--------|---------|--------|--|--|
| (CHIPS) | RGSRH | RGSRL | RGSRH | RGSRL | | |
| 0 | 0x0000 | 0x8000 | 0x0001 | 0x0000 | | |
| 1/2 | 0×0000 | 0xC000 | 0x0001 | 0x8000 | | |
| 1 | 0x0000 | 0x4000 | 0x0000 | 0x8000 | | |
| -1 | 0x0001 | 0x0000 | 0x0002 | 0x0000 | | |

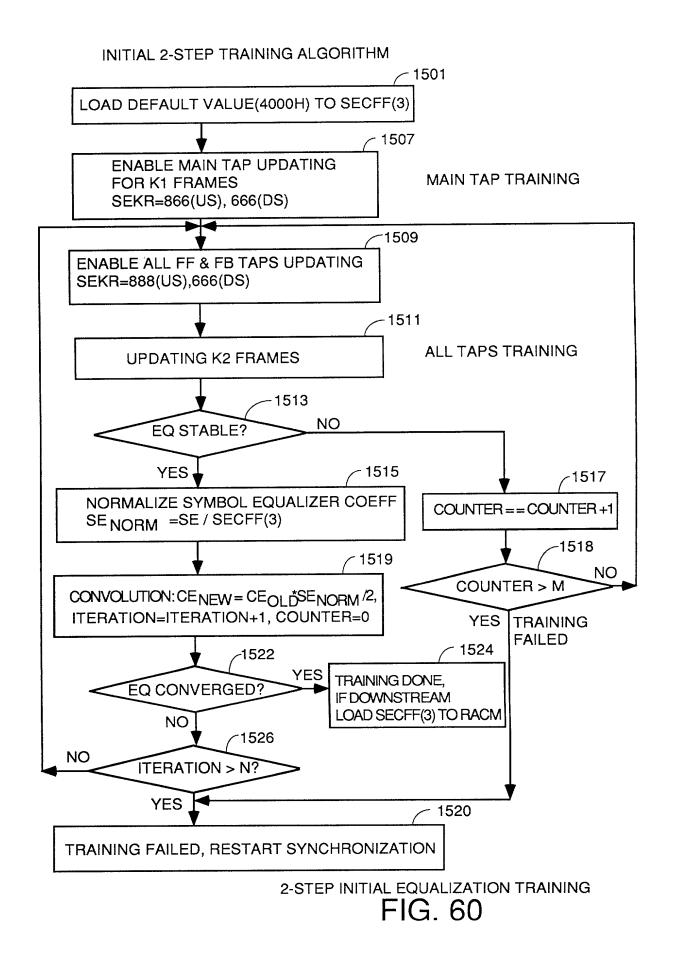


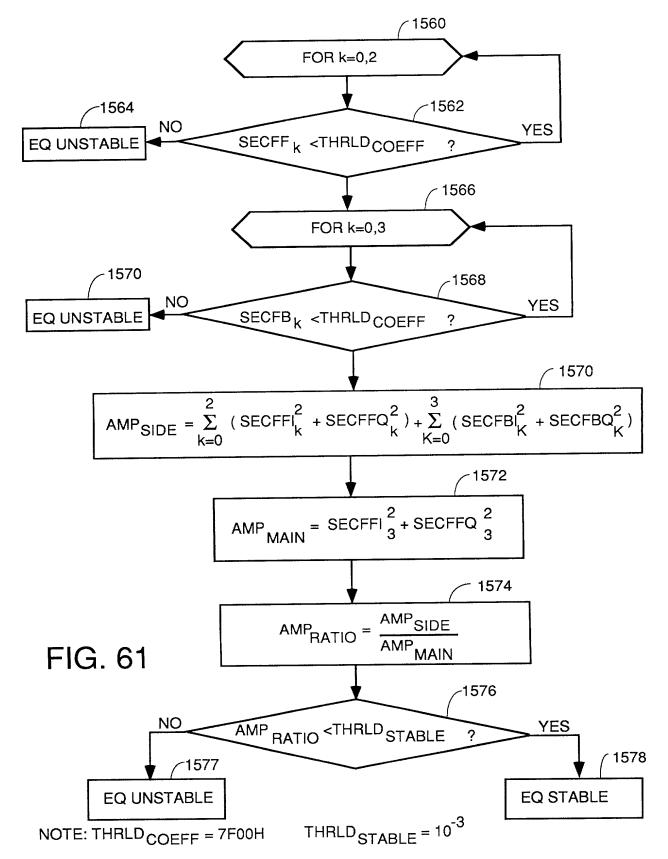
TRAINING ALGORITHM

SE FUNCTION

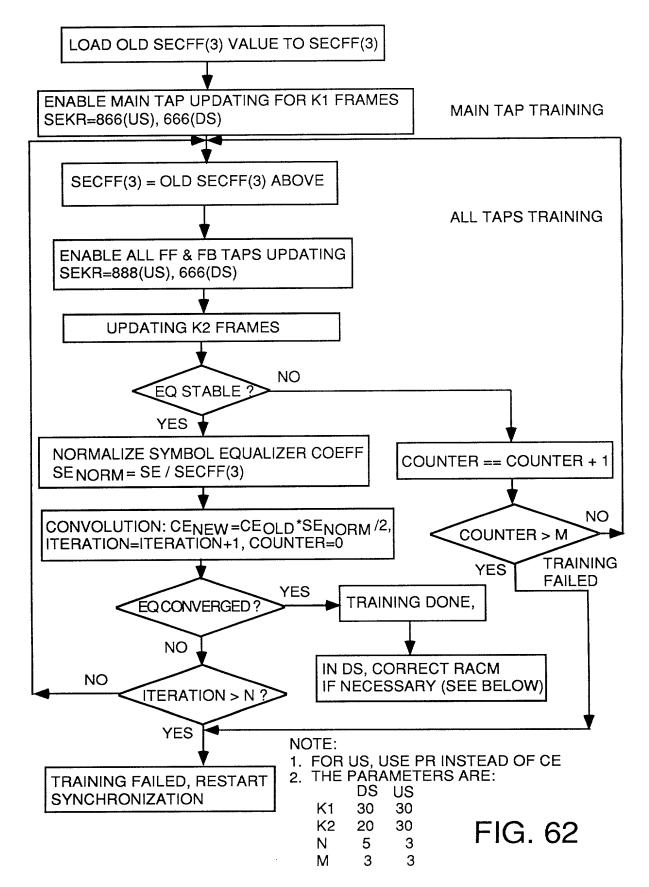




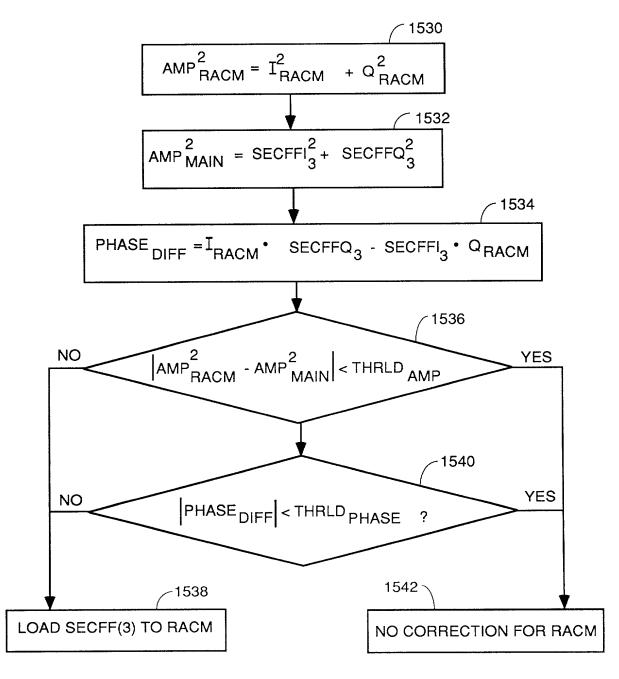




PERIODIC 2-STEP TRAINING ALGORITHM



RACM CORRECTION



NOTE: THRLD_{AMP} = TBD THRLD_{PHASE} = TBD

ROTATIONAL AMPLIFIER CORRECTION

FIG. 63

EQ CONVERGENCE CHECK

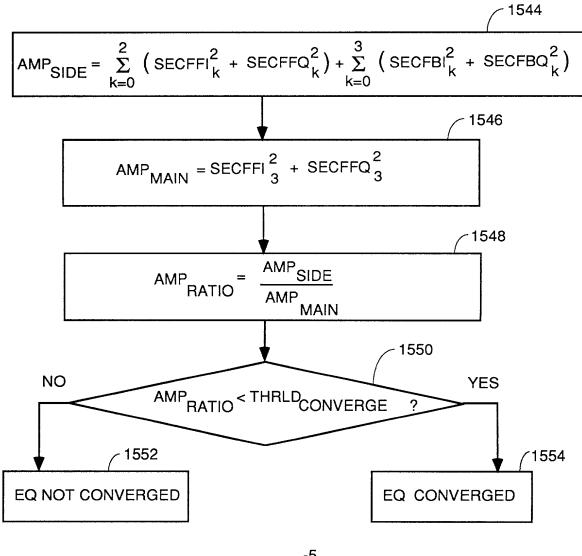
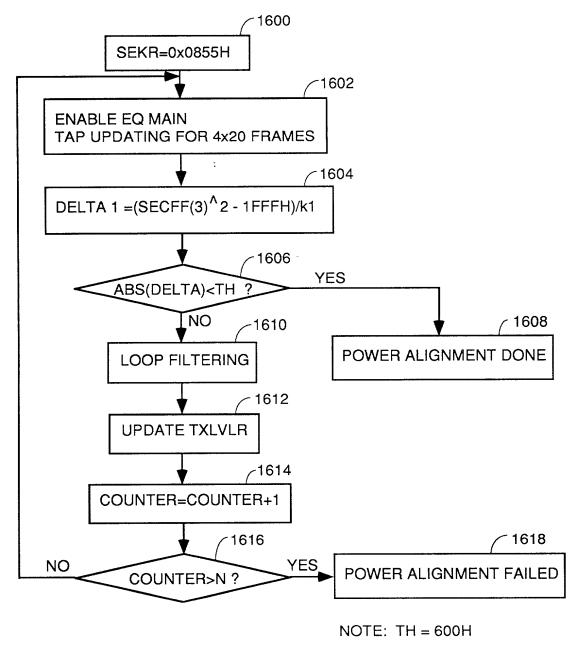




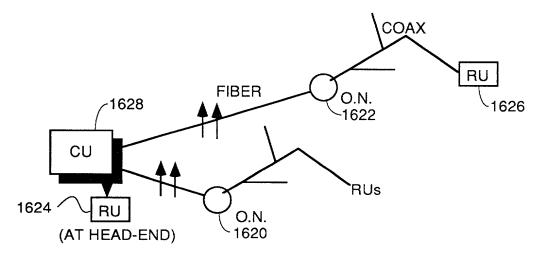
FIG. 64

POWER ALIGNMENT FLOW CHART

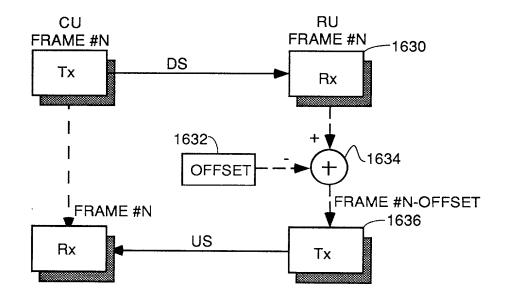


N = 12









TOTAL TURN AROUND (TTA) IN FRAMES = OFFSET FIG. 67

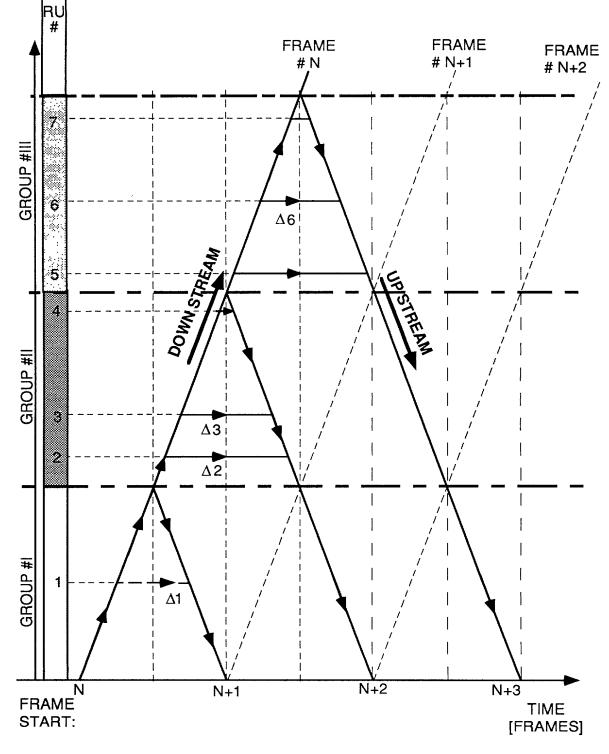
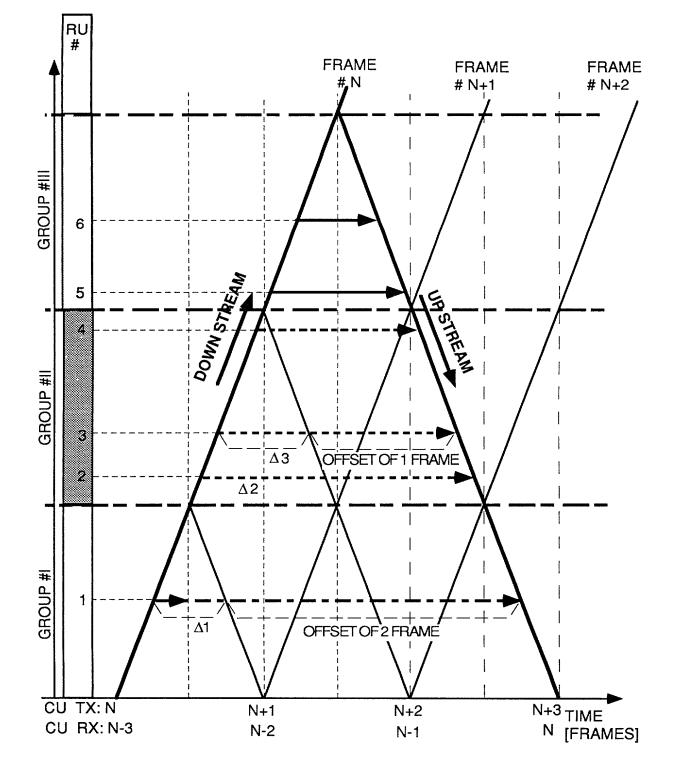


FIG. 68



Control message (downstream) and function (upstream) propagation in a 3 frames tta channel $FIG.\,69$

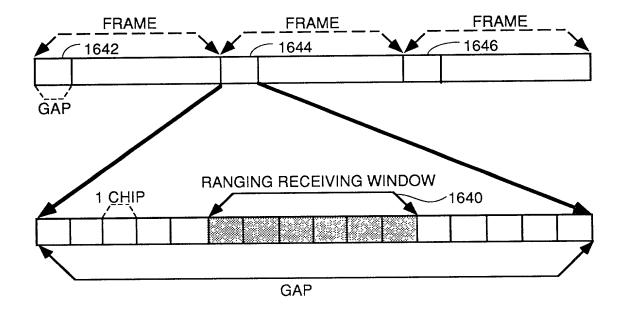
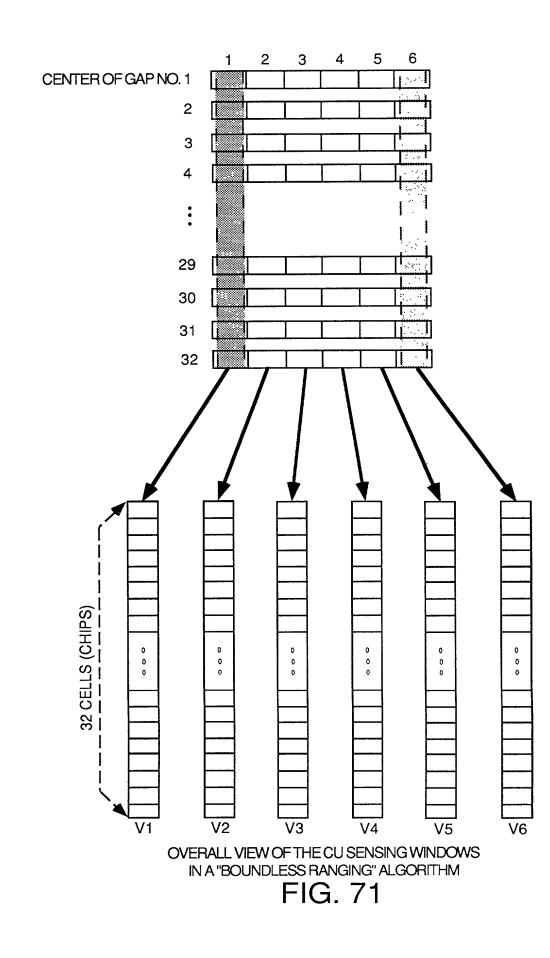


FIG. 70



| CHIP\FR | 1 | 2 | 3 | 4 | 5 | 6 | 7 | | 33 |
|----------------|---|---|---|---|---|---|---|-----|----|
| 1 | 0 | 0 | 1 | 0 | 0 | 1 | 1 | ••• | 0 |
| 2 | 1 | 0 | 0 | 1 | 1 | 1 | 1 | ••• | |
| 3 | 0 | 0 | 0 | 1 | 1 | 1 | | | |
| 4 | 0 | 0 | 0 | | 0 | 0 | 0 | ••• | 0 |
| 5 | 0 | | 0 | 0 | 1 | | | | |
| 6 | 0 | 0 | 1 | 1 | 1 | | | | |
| 7 | 0 | 0 | 0 | 1 | 1 | | | | |
| 8 | 0 | 0 | 0 | 0 | | 0 | 0 | ••• | |

FIG. 72